MFG-100/MFG-100-i



MagnebotiX tabletop magnetic field and gradient control systems

The MagnebotiX MFG-100/100-i systems comprise a tabletop magnetic field generation unit, power electronics, and a control software user interface (MBX Pro). The system is capable of generating arbitrarily oriented magnetic fields and field gradients within a spherical workspace having a diameter of approximately 10 mm. The fields are unrestrained in both translational and rotational degrees-of-freedom (DOF), and thus the system can levitate and control magnetic objects in viscous liquids with 5 degrees of freedom (3-DOF position, 2-DOF orientation). By applying time-varying signals, rotational or stepping-based actuation of magnetic objects is accomplished. With our MBX Control software and its plugin-based architecture, multiple control strategies are possible ranging from manual open-loop control to custom solutions for fully automated servoing of magnetic objects along predefined paths. The MagnebotiX MFG-100-i is adapted for use in an inverted configuration, such as on an inverted microscope.



Field Generation and Control Modes

- *Field control:* generate an arbitrarily oriented field vector within the workspace for magnetizing ferromagnetic objects. Magnetic objects that can move freely will align with the external magnetic field.
- *Gradient control:* exert a force on magnetized objects to pull mobile objects in arbitrary directions along the field gradient or levitate objects in liquids
- *Rotational control:* controllably change the magnetic field orientation to exert a torque on a magnetized object, causing it to reorient if deflectable and rotate freely with the external field if mobile
- User-specific control: define fields and gradients as a function of time using standard mathematical notation: square wave, sawtooth, precessing field vector, exponentially decreasing if you can define it mathematically you can generate with our new software.

Suggested Areas of Application

- Studies of magnetic microactuation strategies through the influence of magnetic forces and torques acting on small magnetic objects in air or liquids
- Selective isolation and extraction of naturally magnetic or magnetically tagged biological and nonbiological objects from viscous liquids
- Mechanical manipulation and extraction of non-magnetic objects in liquids with the help of an untethered magnetic end-effector
- Studies on the mechanical properties of small objects through their interaction with an untethered magnetic end-effector
- Mechanobiology studies at the single cell or engineered tissue level, such as direct mechanical
 interaction with microorganisms and cells, and studies of their behavioral response with an untethered
 magnetic end-effector
- In vivo studies at the small animal level such as zebrafish

System Components

MagnebotiX MFG-100 / 100-i magnetic field and gradient generation unit

- Maximum working volume diameter:
- Max. magnetic field strength (center):
- Max. magnetic field gradient (center):
- Max. magnetic field frequency:
- Max. slew rate per coil at 20 A step input:
- Dimensions (W x D x H):
- Weight:

MagnebotiX ECB820 power unit

- Number of channels:
- Max. current per channel:
- Max. voltage per channel:
- Max. power consumption:
- External power requirements:
- Dimensions (W x D x H):
- Weight:
- Connection to control computer:
- 8 20 A 48 V 1008 W 110 - 240 VAC / 50 - 60 Hz 440 mm x 325 mm x 130 mm 10 kg Ethernet



System safety features: over-temperature and over-current monitoring of all coils; controller shutdown upon loss of communication with coil unit; external emergency shutdown switch.

MagnebotiX HID100 human input devices

Input devices:

Keyboard, mouse, SpaceNavigator (3DCONNEXION), PlayStation3 controller

Microscope, cameras and lenses not included

- Microscope or lenses are determined by the user according to experiments to be performed. Basler USB3 cameras are compatible with our MBX Pro software (plug-and-play (e.g., Basler USB3 ACE or Pulse series).
- Tested products : Stereo (dissecting) microscope with a suitable stand to accommodate the MFG-100 (Olympus, Leitz, etc.)
 - : Edmund VZM 200i 2x zoom lens (WD: 90mm, DOF: 1.5mm) optics.
 - : inverted fluorescence microscope models: Olympus IX 71, 73, 81 and 83; Nikon Eclipse TE2000/Ti-S/Ti2

The principle of the magnetic field generating technology is protected by patents WO 2011029592 A1 and WO 2013127516 A1 to ETH Zurich and sublicensed to MagnebotiX AG. For more details on the MFG100 / MFG100-I systems see S. Schuerle, S. Erni, M. Flink, B. E. Kratochvil, B. J. Nelson, "Three-Dimensional Magnetic Manipulation of Micro- and Nanostructures for Applications in Life Sciences", *IEEE Transactions on Magnetics*, Vol. 49, No. 1, January 2013, pp. 321-330.

The MBX Control software was originally developed ("daedalus") in the Institute of Robotics and Intelligent Systems, Multiscale Robotics Lab, ETH Zürich.

All specifications are subject to change without notice.



20 mT in any direction

300 Hz at 2 mT, 80Hz at 10 mT

250 mm x 275 mm x 110 mm

1 cm

2 T/m

20 T/s

4.5 kg